



COMMENTS ON "A NOVEL APPROACH TO DETERMINE THE FREQUENCY EQUATIONS OF COMBINED DYNAMICAL SYSTEMS"

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(Received 19 December 2001)

In the context of the derivation of the characteristic equation of a continuous structure represented by an *N*-degree-of-freedom (d.o.f.) discrete system to which *s* spring-mass systems are attached, Cha and his co-worker manipulated the corresponding generalized $(N \times N)$ eigenvalue problem so that its characteristic determinant is equivalent to that of a smaller $(s \times s)$ matrix (assumption: $s \ll N$) [1]. In the appendix, they have given the derivation of the corresponding formula for s = 1 and stated that the general case of arbitrary *s* is merely an extension of the given derivation. The aim of this short note is to make a positive comment on the appendix of the above interesting and useful study and to show that the formula for the special case of s = 1 can also be obtained in a shorter way directly, though it may not be generalized for any *s*.

Noting that \mathbf{K}^d and \mathbf{M}^d are diagonal matrices, the problem to be solved is the calculation of the determinant of the matrix $[\mathbf{\Lambda} + \sigma \mathbf{\varphi} \mathbf{\varphi}^T]$, where the diagonal matrix $\mathbf{\Lambda}$ is defined as

$$\mathbf{\Lambda} = [\mathbf{K}^d - \omega^2 \mathbf{M}^d] = \operatorname{diag}(K_i - \omega^2 M_i) \quad (i = 1, \dots, N).$$

Using the well-known formula from the matrix theory [2]

$$det(\mathbf{A} + \alpha \mathbf{b}\mathbf{b}^{\mathrm{T}}) = (det \mathbf{A})(1 + \alpha \mathbf{b}^{\mathrm{T}}\mathbf{A}^{-1}\mathbf{b})$$

for the determinant of the sum of a regular square matrix **A** and a rank-one modification, the following can be written directly:

$$\det(\mathbf{\Lambda} + \sigma \mathbf{\phi} \mathbf{\phi}^{\mathrm{T}}) = (\det \mathbf{\Lambda})(1 + \sigma \mathbf{\phi}^{\mathrm{T}} \mathbf{\Lambda}^{-1} \mathbf{\phi}).$$

The second factor yields

$$1 + \sigma \boldsymbol{\phi}^{\mathrm{T}} \boldsymbol{\Lambda}^{-1} \boldsymbol{\phi} = 1 + \sigma [\phi_1 \cdots \phi_N] \operatorname{diag} \left(\frac{1}{K_i - \omega^2 M_i} \right) \begin{bmatrix} \phi_1 \\ \vdots \\ \vdots \\ \phi_N \end{bmatrix} = 1 + \sigma \sum_{i=1}^N \frac{\phi_i^2}{K_i - \omega^2 M_i},$$

which is exactly the result given in the appendix of reference [1].

0022-460X/02/\$35.00

LETTERS TO THE EDITOR

REFERENCES

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- 2. P. LANCASTER and M. TISMENETSKY 1985 *Theory of Matrices* 65. New York: Academic Press, second edition.